

Why is $|H(\omega)|^2 = \frac{\text{PSD}(\text{output})}{\text{PSD}(\text{input})}$?

Def'n of transfer function:

$$L X = f$$

$$X = H(\omega)e^{i\omega t} \quad \& \quad f = e^{i\omega t}$$

↑ this is the transfer function.

Facts about Four Transf.

$$1 = \int_{-\infty}^{\infty} \delta(t) e^{-i\omega t} dt \quad f \equiv \frac{\omega}{2\pi}$$

$$\delta(t) = \int_{-\infty}^{\infty} 1 e^{+i2\pi f t} df$$

Transfer function H with the factor $e^{i\omega t}$,
 is the response to $e^{i\omega t}$
 "impulse response" is the response to an impulse:

$$L X_{\text{impulse}}(t) = \delta(t)$$

Fact: $H(\omega)$ is the F.T. of X_{impulse} .

Why?

$$L X_{\text{impulse}} = \delta(t)$$

linear $\rightarrow L \int_{-\infty}^{\infty} \tilde{x}(\omega) e^{i\omega t} d\omega = \int_{-\infty}^{\infty} 1 e^{i\omega t} d\omega$

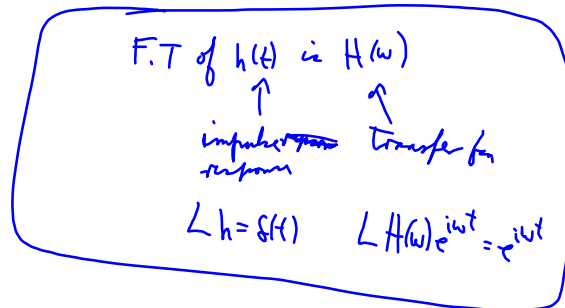
$$\int_{-\infty}^{\infty} [L \tilde{x}(\omega) e^{i\omega t}] d\omega = \int_{-\infty}^{\infty} e^{i\omega t} d\omega$$

$$\text{So } L \tilde{x}(\omega) e^{i\omega t} = e^{i\omega t}$$

the $e^{i\omega t}$ is the response to $e^{i\omega t}$, so

$\tilde{x}(\omega)$ is the transf. fun. $H(\omega)$.

So rewrite $X_{\text{impulse}}(t)$ as " $h(t)$ ".



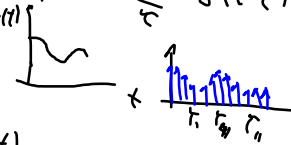
Fact: $L x = f$ $L h(t) = \delta(t)$

$$\Rightarrow x(t) = \int_{-\infty}^{\infty} f(\tau) h(t-\tau) d\tau$$

Physical proof:

$f(t) \rightarrow$ smoothing bowing action on a violin.

high speed photo $\Rightarrow f(t) = \sum_{\tau} a(\tau) \delta(t-\tau)$

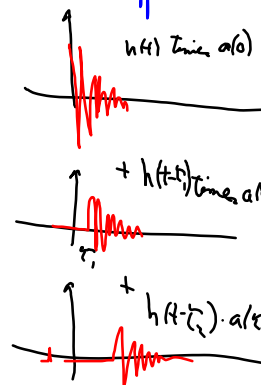


response to $\delta(t)$



is $h(t)$

response to $f(t)$ is



$$x(t) = \sum_{\tau} a(\tau) h(t-\tau) \text{ when } f(t) = \sum_{\tau} a(\tau) \delta(t-\tau)$$

$$x(t) = \int_{-\infty}^{\infty} f(\tau) h(t-\tau) d\tau \quad \leftarrow \quad f(t) = \int_{-\infty}^{\infty} f(\tau) \delta(t-\tau) d\tau$$

Fact: $L x = f$ $L h(t) = \delta(t)$

$$\Rightarrow x(t) = \int_{-\infty}^{\infty} f(\tau) h(t-\tau) d\tau$$

Math proof

$$L x = L \int_{-\infty}^{\infty} f(\tau) h(t-\tau) d\tau$$

$$= \int_{-\infty}^{\infty} f(\tau) \underbrace{L h(t-\tau)}_{\delta(t-\tau)} d\tau$$

$$= f(t)$$

$$x(t) = \int_{-\infty}^{\infty} f(\tau) h(t-\tau) d\tau$$

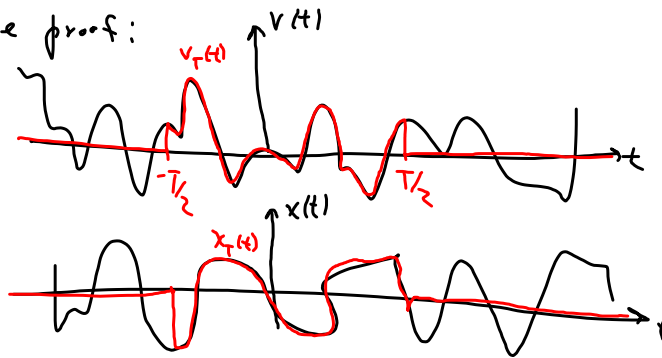
Four Trans

$$X(\omega) = F(\omega) H(\omega)$$

SO: why is $PSD_{x(t)} = |A(\omega)|^2 PSD_{v(t)}$

$L x = v$ ~~random~~ v random. ?

False proof:



$L x(t) = v(t)$

truncate $L x_T(t) = v_T(t)$ not quite true: $x(t)$ continues to reverberate, $x(t) \neq x_T(t)$.

accept this.

$$x_T(t) = \int_{-\infty}^{\infty} v_T(t) h(t-t) dt$$

$$\hat{x}_T(\omega) = \hat{v}_T(\omega) H(\omega)$$

$$\frac{|\hat{x}_T(\omega)|^2}{T} = \frac{|\hat{v}_T(\omega)|^2}{T} |H(\omega)|^2$$

$$PSD_{x(t)} = PSD_{v(t)} |H(\omega)|^2$$

True Proof.

$$L_{x(t)} = v(t)$$

$$E\{x(t) L_{x(t)}\} = E\{x(t) v(t)\}$$

"

$$L\{E\{x(t) x(t)\}\}$$

"

$$L R_x(t) = E\{x(t) v(t)\}$$

$$R_x(t) = \int_0^{\infty} E\{x(t) v(\tau)\} h(t-\tau) d\tau$$

$$E\{v(t) \int_{-\infty}^{\infty} v(\tau') h(t-\tau') d\tau'\}$$

$$E\{v(t) v(\tau')\} h(t-\tau')$$

$$R_v(\tau-\tau')$$

$$R_x(t) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} R_v(\tau-\tau') h(t-\tau) d\tau' d\tau$$

FT

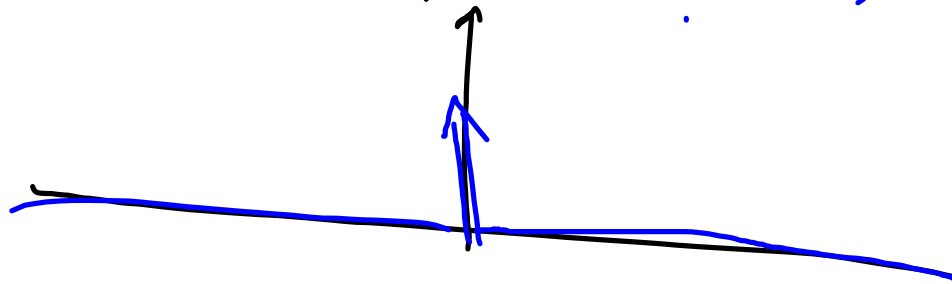
$$PSD_x(\omega) = \underbrace{FT\{h(t)\}}_{FT[R_v]} \cdot \underbrace{FT\{h(\tau)\}}_{H(\omega)^*} \cdot H(\omega)$$

$$PSD_x = PSD_v \cdot |H(\omega)|^2$$

White noise - no autocorrelation.

$$\mathcal{E}[v(t)v(t')] = 0 \text{ if } t \neq t'$$

$$R_x(\tau) = \sigma^2 \delta(\tau)$$



$$R_x(0) = \mathcal{E}[x(t)x(t)] = \mathcal{E}[x(t)^2] = \sigma^2$$

$$FT[R_x(\tau)] = PSD = \int_{-\infty}^{\infty} R_x(\tau) e^{-i\omega\tau} d\tau = \sigma^2$$

